

Goal-Oriented Chatbot Dialog Management Bootstrapping with Transfer Learning

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Goal-Oriented (GO) Chatbots

Three key elements:

1. **Goal**: help users achieve a predefined goal
2. **Domain**: e.g. movie booking
3. **Slots and intents**:
inform(date = 'tomorrow')

Low in-domain data availability

- Non-trivial data requirements
- Limited in-domain data
- Obtaining and labeling in-domain data is hard

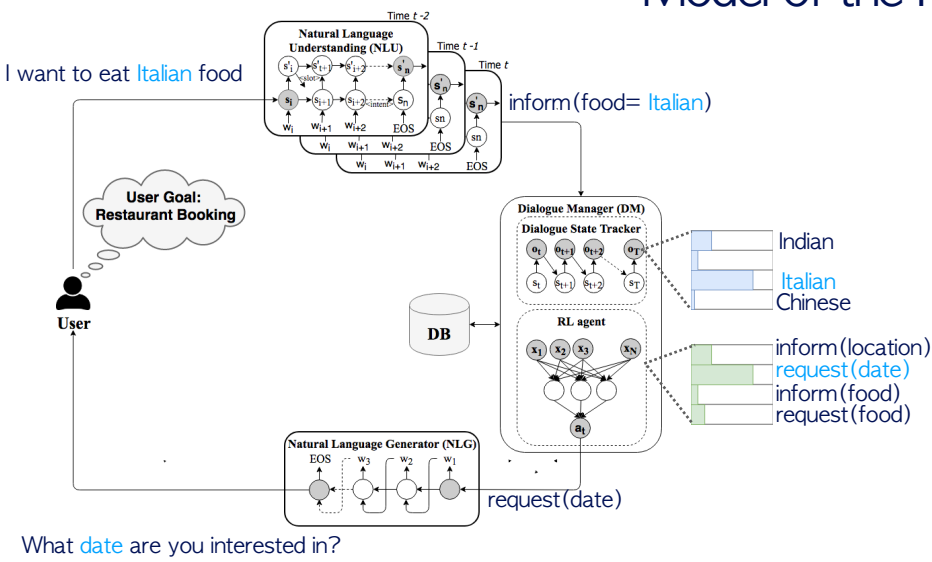
Leverage domain similarity

Transfer the knowledge from one SOURCE domain to another TARGET domain

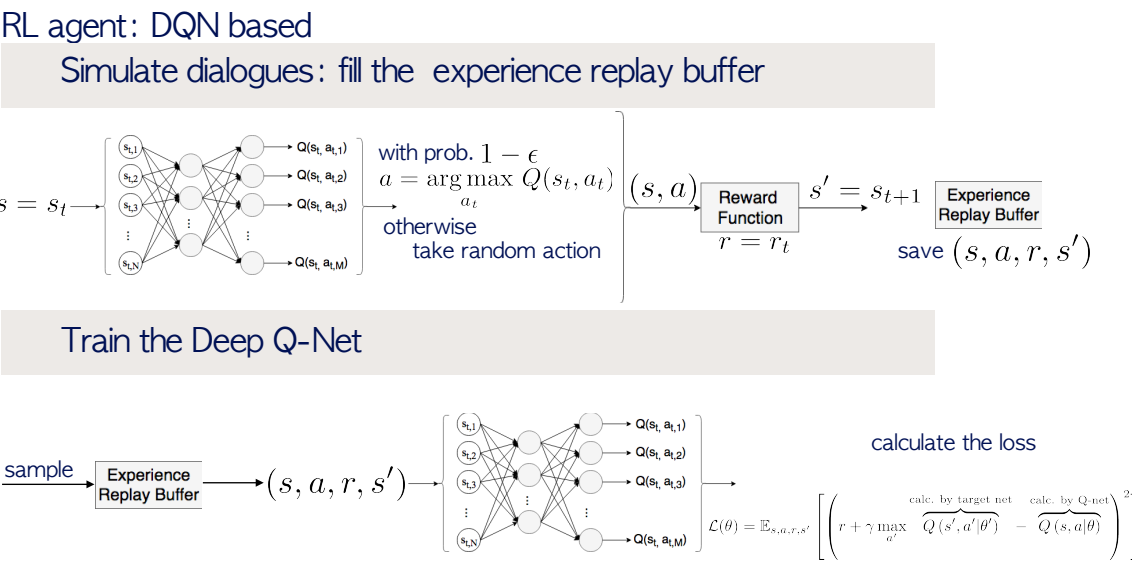
Contributions

1. Training GO chatbots with less data: models trained with transfer learning achieve better performance
2. Better GO chatbots: positive effect when all domain data is available
3. Transfer learning is complementary to the warm-starting technique

Model of the RL-based GO Chatbots



Modeled as a Partially Observable Markov Decision Process



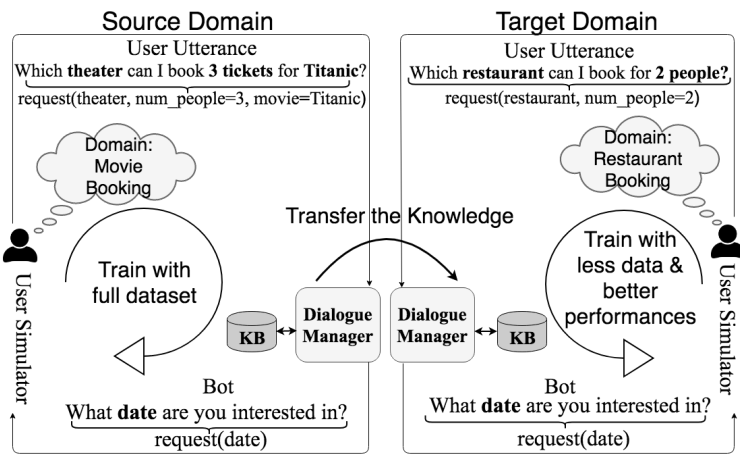
Intuition

Dialog state depends on the type of slots

| Domain 1 Movie Booking | | Domain 2 Restaurant Booking | |
|---------------------------|---------|--------------------------------|------------|
| I | O | O | Where |
| want | O | O | in |
| to | O | O | B-City |
| book | O | O | London |
| tickets | O | O | I |
| for | O | O | can |
| Titanic | B-Movie | O | find |
| for | O | O | an |
| today | B-Date | O | restaurant |
| somewhere | O | O | for |
| in | O | O | B-Date |
| London | B-City | O | tomorrow |

Share common information => Transfer the knowledge

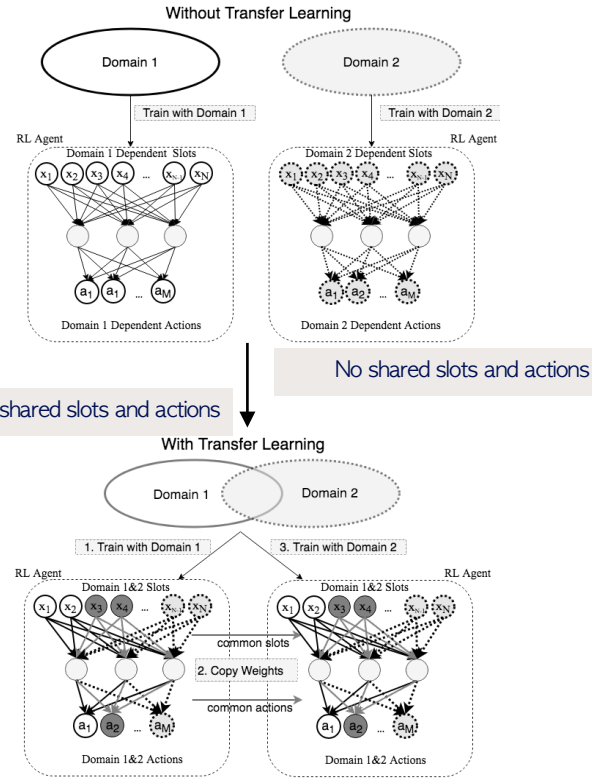
Transfer Learning



Relaxed model: no NLU and NLG units
=> semantic frame level execution

Semantic Frames: set of slot-value pairs

How?



How do we experiment?

Domain overlapping

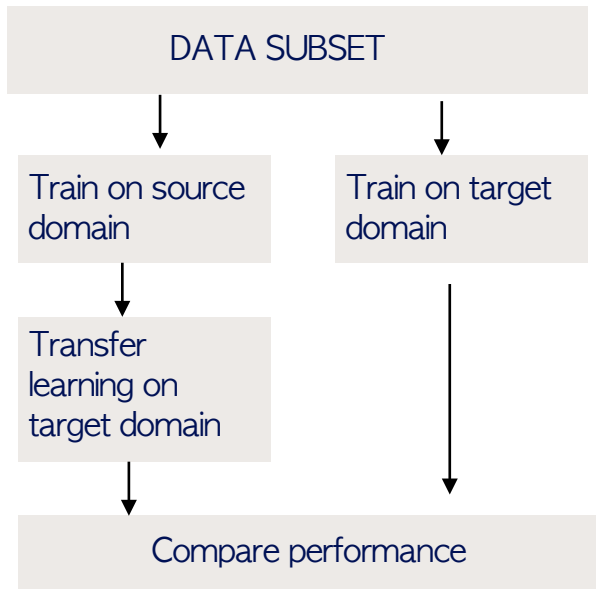
Domain extension

SOURCE: Movie booking

SOURCE: Restaurant booking

TARGET: Restaurant booking

TARGET: Tourist info



Results

Total of 120 training user goals and 32 testing user goals

Subset of n user goals: (5, 10, 20, 30, 50, 120)

